

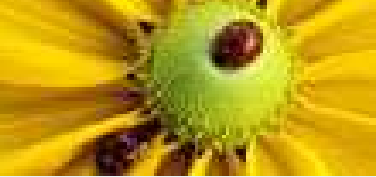
# An approximation problem in computing electoral volatility

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## Introduction

- Short description of the problem setting
- Short description of the paper

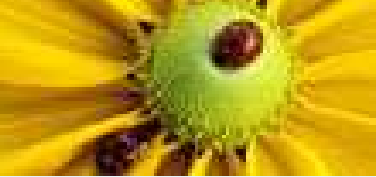
Approximation of volatility

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Approximations of volatility and errors

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# Introduction



# Short description of the problem setting

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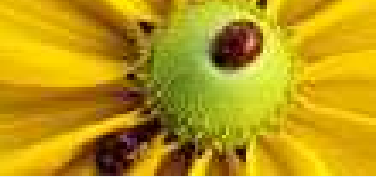
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- This paper is focused on an approximation problem which often arises when volatility is computed from electoral databases.



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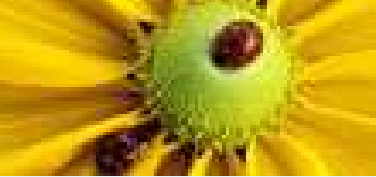
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- Volatility is a key dimension in studies on electoral change or stability in party systems (Pedersen, 1979).



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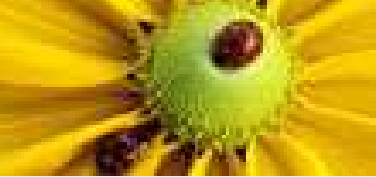
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- This paper is focused on an approximation problem which often arises when volatility is computed from electoral databases.
- Volatility is a key dimension in studies on electoral change or stability in party systems (Pedersen, 1979).
- Though the volatility formula offers no mathematical complexity, its application to real data may present several problems.



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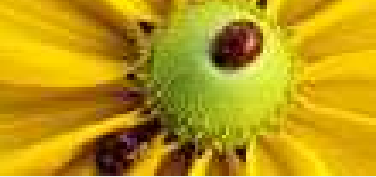
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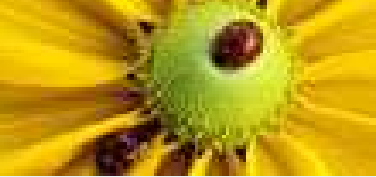
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  - ◆ Bartolini and Mair's (BM) approach is justified through the analysis of its approximation error here derived.



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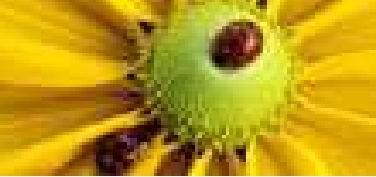
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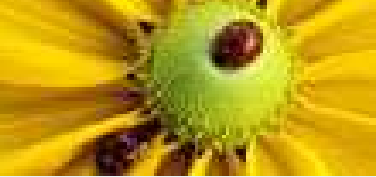
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- It is proved that such new approximations are an improvement of the BM approximation.



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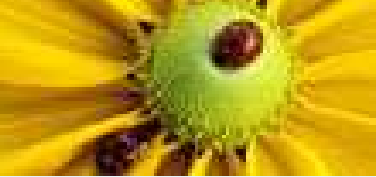
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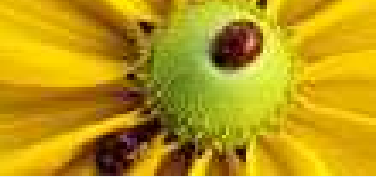
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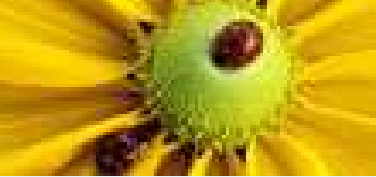
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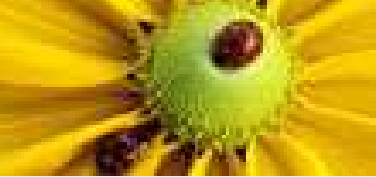
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Consider two elections whose patterns of change are going to be quantified. Assume that each competing unit (party, coalition, etc.) is denoted by an integer in  $\mathcal{I} = \{1, \dots, N\} \subset \mathbb{N}$ .



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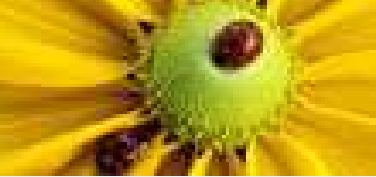
Consider two elections whose patterns of change are going to be quantified. Assume that each competing unit (party, coalition, etc.) is denoted by an integer in  $\mathcal{I} = \{1, \dots, N\} \subset \mathbb{N}$ .

**Electoral Data:**,

$$\{(p_i, q_i) : i \in \mathcal{I}\} ,$$

where  $p_i$  and  $q_i$  stand for the electoral strengths (votes, seats, etc.) of the (party) unit  $i \in \mathcal{I}$  in both elections, respectively.

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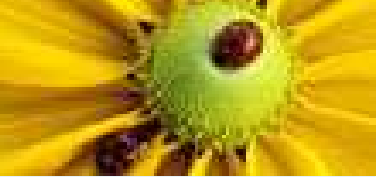
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Suppose that

$$\sum_{i=1}^N p_i = \sum_{i=1}^N q_i = 1. \quad (1)$$

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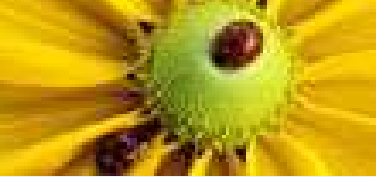
$$\sum_{i=1}^N p_i = \sum_{i=1}^N q_i = 1. \quad (1)$$

To measure the electoral change, the PV measure (Pedersen, 1979) could be computed by

$$V = \frac{1}{2} \sum_{i=1}^N |p_i - q_i|. \quad (2)$$



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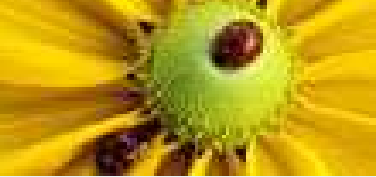
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To measure the electoral change, the PV measure (Pedersen, 1979) could be computed by

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Though the PV formula is very simple, the following computational problems can arise.



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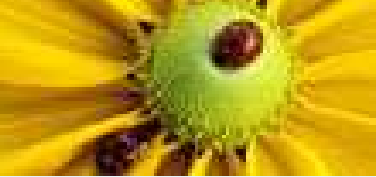
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Problem 1: when the parties in both elections are not the same.



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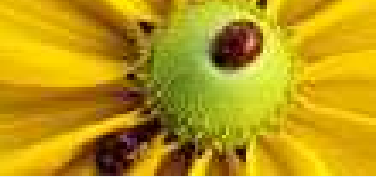
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Problem 1: when the parties in both elections are not the same.

Solution: Guidelines proposed in Bartolini and Mair (1990, Appendix 1, pp. 311–312)



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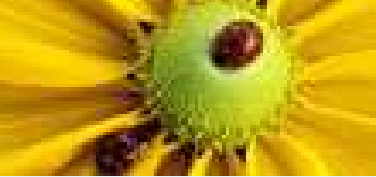
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Problem 2 (the target of this paper): when a part of electoral data is unknown.



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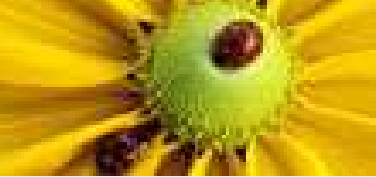
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Problem 2 (the target of this paper): when a part of electoral data is unknown.

Some situations:

- When the party category *Others* appears in the electoral data and no information is given for parties included in this category (Bartolini and Mair, 1990, Appendix 1).
- When details on parties with non significant strength are omitted to maintain memory capabilities under minimum requirements in databases.
- When the researcher is only interested in *relevant parties* (Sartori, 1976, p. 122) and, thus, those non-relevant parties are not considered for the BM rules



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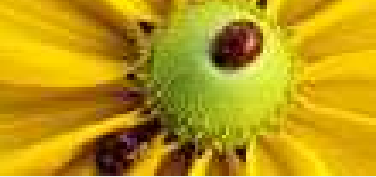
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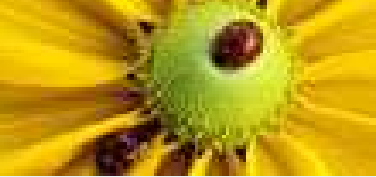
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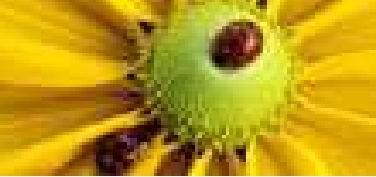
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Problem 2 (the target of this paper): when a part of electoral data is unknown.

**Consequence:**  $V$  cannot be evaluated.





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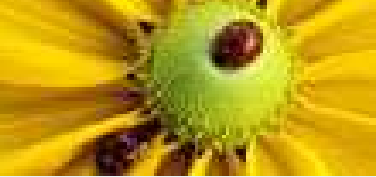
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**Problem 2** (the target of this paper): when a part of electoral data is unknown.

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**Problem formulation:** assume that some of the pairs in  $\{(p_i, q_i) : i \in \mathcal{I}\}$  are unknown.



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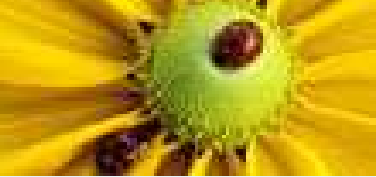
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In this paper the approximation of  $\mathbb{V}$  in such a framework is analyzed.



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# Approximations of volatility and errors



# Problem setting

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Assume that only  $M$  pairs of strengths are the available data, for any  $M \in \mathcal{I}$ , which are given by

$$\{(p_k, q_k) : k = 1, \dots, M\} \subseteq \{(p_i, q_i) : i \in \mathcal{I}\} .$$



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$\{(p_j, q_j) : j = M + 1, \dots, N\}$  is not available.



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 $\mathbb{V}$  is then unknown.



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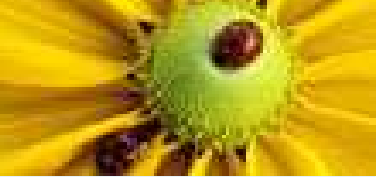
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A naive approximation of  $V$  is given by

$$V[M] = \frac{1}{2} \sum_{k=1}^M |p_k - q_k|, \quad (2)$$

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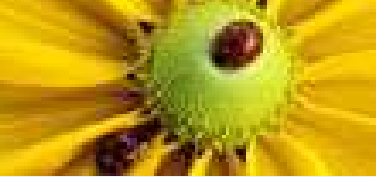
Among other results, **Proposition 1** demonstrates that

$$0 \leq V[M] \leq VL[M] \leq V \leq VU[M], \quad \forall M \in \mathcal{I},$$

where



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where

$$VL[M] = V[M] + \frac{1}{2} |P[M] - Q[M]| \quad \text{and} \quad (2)$$

$$VU[M] = V[M] + \frac{1}{2} (P[M] + Q[M]), \quad \forall M \in \mathcal{I}. \quad (3)$$

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$$P[M] = 1 - \sum_{k=1}^M p_k \quad \text{and}$$

$$Q[M] = 1 - \sum_{k=1}^M q_k, \quad \forall M \in \mathcal{I}. \quad (4)$$

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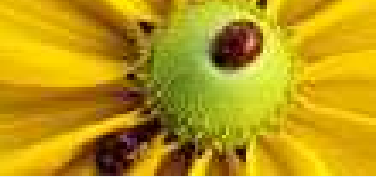
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**Remark:**  $VL[M]$  is the BM approximation. It was used in Bartolini and Mair (1990).



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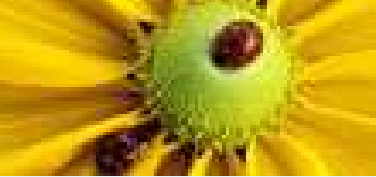
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The study of the error for the BM approximation suggests an alternative approach given by

$$V_{\theta}[M] = \theta VU[M] + (1-\theta) VL[M], \quad \forall M \in \mathcal{I} \text{ and } \forall \theta \in [0, 1]. \quad (4)$$



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It is distinguished the approximation given by

$$VA[M] = V_{1/2}[M] = V[M] + \frac{1}{2} \max\{P[M], Q[M]\}$$

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where

$$1/2 = \arg \min_{\theta \in [0,1]} EC_{\theta}[M]$$



# Upper error bounds

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In these paper, it is derived that

$$EA[M] \leq EC_{\theta}[M] \leq EBM[M], \quad \forall \theta \in [0, 1] \text{ and } \forall M \in \mathcal{I},$$

where

- $EA[M]$ : the upper error bound of  $VA[M]$ ,
- $EC_{\theta}[M]$ : the upper error bound of  $V_{\theta}[M]$ ,
- $EBM[M]$ : the upper error bound of  $VL[M]$ .



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- $EA[M]$ : the upper error bound of  $VA[M]$ ,
- $EC_{\theta}[M]$ : the upper error bound of  $V_{\theta}[M]$ ,
- $EBM[M]$ : the upper error bound of  $VL[M]$ .

Moreover, it is proved that

$$EA[M] = \frac{1}{2} EBM[M] .$$



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